

Adversaries with Limited Information in the Friedkin-Johnsen Model

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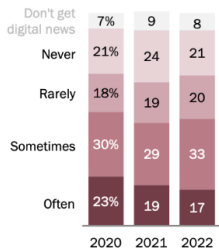
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Online Social Networks (OSNs)



News consumption on social media

% of U.S. adults who get news from social media ...



Note: Figures may not add up to 100% due to rounding.

Source: Survey of U.S. adults conducted July 18-Aug. 21, 2022.

PEW RESEARCH CENTER

- Online social networks (OSNs) have become ubiquitous parts of modern societies
- People use OSNs to stay in touch with their friends, to read news and discuss societal issues
- Some concerns arise, e.g.,
 - State actors use bots to adversarially attack societies and to increase social **discord**

Malicious Actors are Attacking OSNs



(The New York Times, 2016)

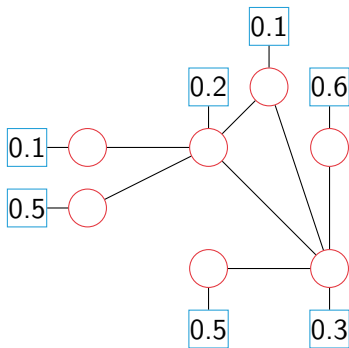
- 2016 Democratic National Committee email leak.
 - *Russian military and intelligence services have been using the Internet to sow discord and discredit legitimate political institutions.* (TIME, 2016)

Our Goal

Achieving a theoretical understanding of the consequence of malicious actors

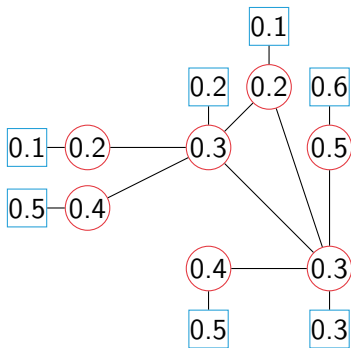
- Model social networks as graphs
- We formulate the *intervention* of the adversary as an *optimization problem*
 - *Intervention*: the effects after conducting some activities in the network:
 - ▶ Spreading fake news \Rightarrow changing people' *opinions*
 - Objective function encodes the desired goal
 - Constraints encode the power of the *intervention*
- We consider the *opinion formation model* as an abstraction of users' *opinions*
 - DeGroot Model, Bounded Confidence Model, *Friedkin-Johnsen Model*...
 - The societal discord is measured by the *opinions*

A Glimpse on Friedkin-Johnsen Model



- The graph $G = (V, E, w)$, \mathbf{L} is the graph Laplacian
- Nodes with their *fixed, private innate* opinions
- $s_u \in [0, 1]$

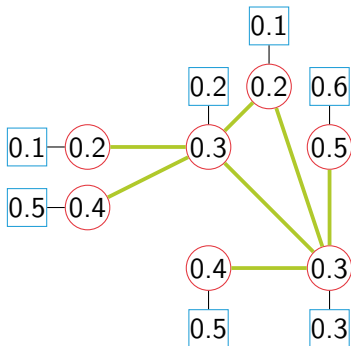
A Glimpse on Friedkin-Johnsen Model



- Due to peer pressure, the nodes *share different public expressed* opinions
- $z_u^t \in [0, 1]$ changes on time t
- $$z_u^t = \frac{s_u + \sum_{v \in N(u)} w_{uv} z_v^{(t-1)}}{1 + \sum_{v \in N(u)} w_{uv}}$$
- At the equilibrium state $\mathbf{z}^* = (\mathbf{I} + \mathbf{L})^{-1} \mathbf{s}$

Measure Societal Discord by Users' Opinions

For instance, disagreement, polarization



- The **disagreement** measures the differences between **expressed** opinions

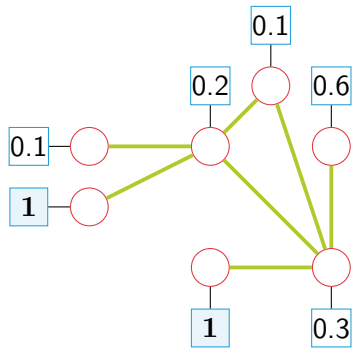
$$\mathcal{D}_{G,s} = \sum_{(u,v) \in E} w_{u,v} (z_u^* - z_v^*)^2 = \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s}$$

- $\mathcal{D}(\mathbf{L}) = (\mathbf{L} + \mathbf{I})^{-1} \mathbf{L} (\mathbf{L} + \mathbf{I})^{-1}$
- **Disagreement** is determined by *network structure* and *innate opinions*.

How Much Disagreement Can Malicious Actors Sow on Online Social Networks

Maximize Disagreement with Full Information

Chen, Racz (TNSE'21) and Gaitonde, Kleinberg, Tardos (EC'20)



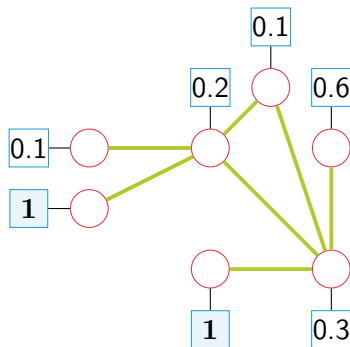
Problem (Full-information)

Maximize *disagreement* by radicalizing k users' innate opinions, given the network structure and innate opinions.

$$\begin{aligned} \max_{\mathbf{s}} \quad & \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s}, \\ \text{s.t.} \quad & \|\mathbf{s} - \mathbf{s}_0\|_0 = k, \text{ and} \\ & \mathbf{s}(u) \in \{\mathbf{s}_0(u), \mathbf{1}\} \text{ for all } u \in V. \end{aligned}$$

Maximize Disagreement with Full Information

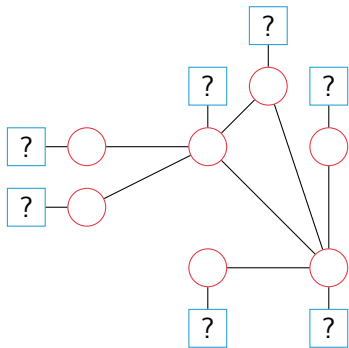
Chen, Racz (TNSE'21) and Gaitonde, Kleinberg, Tardos (EC'20)



- They show that disagreement increases by at most $8d_{\max}k$
- They conducted some heuristics, like greedy algorithm and changing the opinions of centrists
- Adversaries in the full-information setting are quite powerful

Our Paper: Maximize Disagreement with Limited Information

Maximize Disagreement with Limited Information



True innate opinions \mathbf{s}_0 are very hard to obtain

- It still knows the network structure
- It still has the power to radicalize opinions

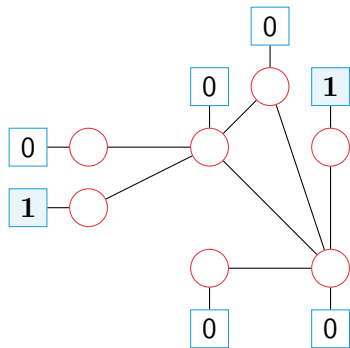
$$\max_{\mathbf{s}} \mathbf{s}^T \mathcal{D}(\mathbf{L}) \mathbf{s},$$

$$s.t. \quad \|\mathbf{s} - \mathbf{?}\|_0 = k, \text{ and}$$

$$\mathbf{s}(u) \in \{?, 1\} \quad \forall u \in V.$$

What strategy can the malicious actor apply?

Maximize Disagreement with Limited Information



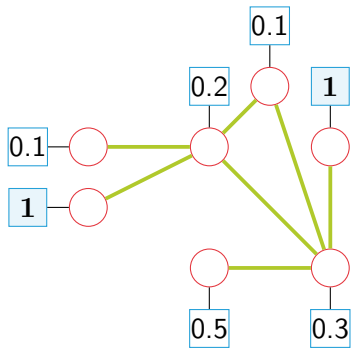
Problem (Limited-information)

Maximize *disagreement* by radicalizing k users' innate opinions, given **only** the network structure.

$$\begin{aligned} \max_{\mathbf{s}} \quad & \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s}, \\ \text{s.t.} \quad & \|\mathbf{s} - \mathbf{0}\|_0 = k, \text{ and} \\ & \mathbf{s} \in \{0, 1\}^n. \end{aligned}$$

It might select different nodes to radicalize.

Maximize Disagreement with Limited Information



Theorem (informal)

Assume that the initial *innate* opinions have *small variance* (achieved by technical assumptions):

- $\mathcal{O}(1)$ -approximation algorithm to Limited-information problem \Rightarrow $\mathcal{O}(1)$ -approximation solution Full-information problem.
- Adversaries with limited information are almost as powerful as with full information

Limited-information Problem: Cardinality-Constrained Max-Cut Variant

On graph with positive and **negative** edge weights

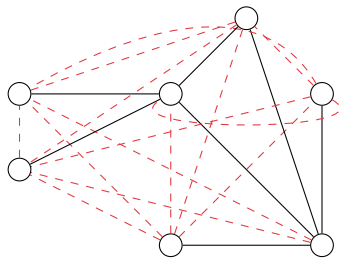


Figure: The graph Laplacian of the graph is $\mathcal{D}(\mathbf{L})$. Negative weights edges are in red.

Regard the **disagreement** matrix $\mathcal{D}(\mathbf{L})$ as a graph Laplacian

- This problem is **NP**-hard and no longer submodular
- We apply Semidefinite Program (SDP) Relaxation and hyperplane rounding to get a initial *cut*
- We bound the loss on *cut* on each greedy move

Theoretical results on Limited-information Problem

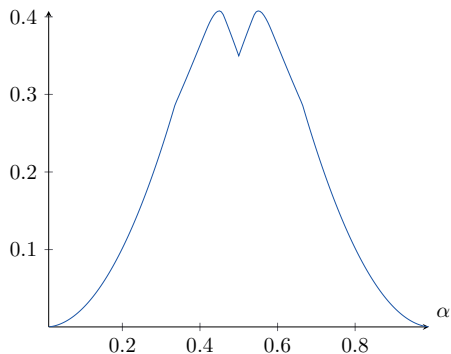


Figure: Approximation Ratio. $k = \alpha n$.

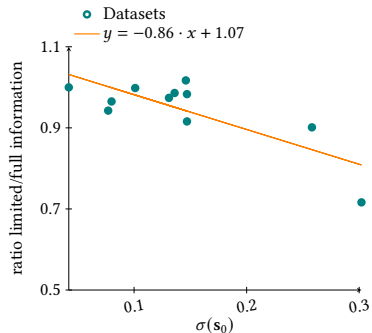
Theorem (informal)

If $k \in \Omega(n)$, there exists a randomized $\Omega(1)$ -approximation algorithm for the limited-information problem that succeeds with high probability.

- We set $k \in \Omega(n)$ due to technical difficulties

Experiments

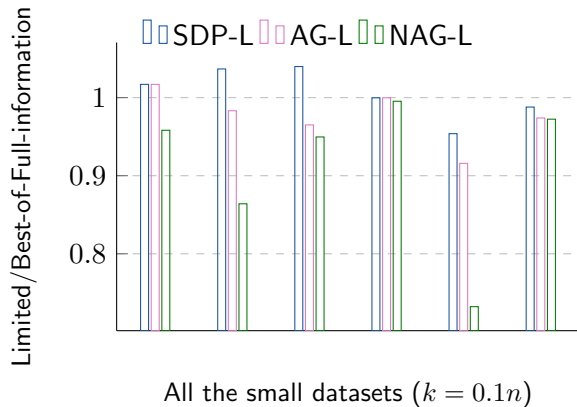
The Factor that Influences the Performance



Strong relationship between initial standard deviation of the innate opinions and performance of limited-information methods

Figure: Standard deviation of opinions, $R^2 = 0.62$

SDP-L is the Best Among Limited-information Algorithms



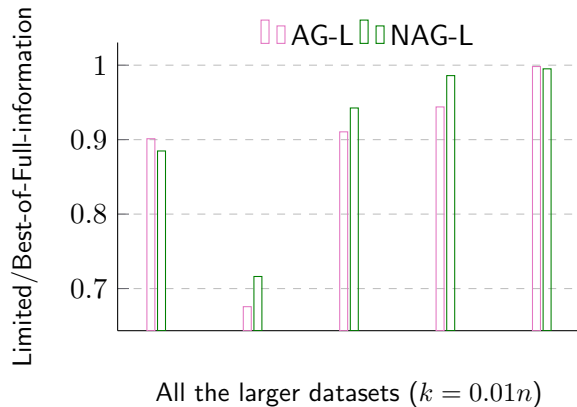
Limited-information algorithm:

SDP-L: SDP-based

AG-L: Adaptive-Greedy

NAG-L: NonAdaptive-Greedy

Limited-information is at Most a Factor of 1.4 Worse



Limited-information algorithm:

AG-L: Adaptive-Greedy

NAG-L: NonAdaptive-Greedy

Summary

- Our paper studies the adversary's potential to increase societal discord
- We formally prove that this adversary with limited information is almost the same powerful as the adversary with full information
- We propose a constant approximation ratio algorithm for the problem under the limited information when $k = \Omega(n)$
- We evaluate our algorithms in real-world datasets

Open Questions



- Can we design a faster algorithm?
- The graph with positive and negative edge weights is extremely dense, can we find a sparser substitute of it?
- Can we design an approximation algorithm when $k = o(n)$?
- Is it possible to verify our algorithm in real world?

Adversaries with Limited Information in the Friedkin–Johnsen Model

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Appendix: How to Solve the Limited-information Problem?

Limited-information Problem is a MaxCut Variant

Observe (1) $\mathcal{D}(\mathbf{L}) \mathbf{1} = \mathbf{0}$; and (2) $\mathcal{D}(\mathbf{L})$ is positive semidefinite.

$\mathcal{D}(\mathbf{L}) = D' - W'$, where $W'_{ii} = 0$ and

$$D'_{ii} = \sum_j W'_{ij}.$$

$$\mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s} = \frac{1}{2} \sum_{i,j} W'_{i,j} (s_i - s_j)^2.$$

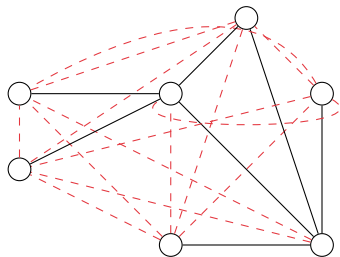
$$\max_{\mathbf{s}} \quad \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s},$$

$$s.t. \quad \|\mathbf{s}\|_0 = k, \text{ and}$$

$$\mathbf{s} \in [0, 1]^n.$$

Limited-information Problem is a MaxCut Variant

$\mathcal{D}(\mathbf{L}) = D' - W'$, and we treat W' as a new weighted adjacency matrix on $G' = (V, W')$.



$$\begin{aligned} \max_{\mathbf{s}} \quad & \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s}, \\ \text{s.t.} \quad & \|\mathbf{s}\|_0 = k, \text{ and} \\ & \mathbf{s} \in [0, 1]^n. \end{aligned}$$

Limited-information Problem is a MaxCut Variant

How to solve the MaxCut with k nodes on one side on the G' ? (**NP**-hard, reduction from MaxCut)

- Applying Linear relaxation:
 $\frac{1}{2}$ -approximation algorithm for all k .
- Applying Semidefinite relaxation:
> 0.63-approximation algorithm,
when $k = \frac{1}{2}n$.
- Applying SOS hierarchy:
> 0.85-approximation algorithm,
when $k = \Omega(n)$.

$$\begin{aligned} \max_{\mathbf{s}} \quad & \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s}, \\ \text{s.t.} \quad & \|\mathbf{s}\|_0 = k, \text{ and} \\ & \mathbf{s} \in [0, 1]^n. \end{aligned}$$

Solve Limited-information Problem with Semidefinite Programming

$$\begin{aligned} \max_{\mathbf{v}_1, \dots, \mathbf{v}_n} \quad & \frac{1}{4} \sum_{ij} \mathcal{D}(\mathbf{L})_{ij} \mathbf{v}_i^\top \mathbf{v}_j, \\ \text{s.t.} \quad & \sum_{i < j} \mathbf{v}_i^\top \mathbf{v}_j = \frac{1}{2} n^2 (1 - 2\alpha)^2 - \frac{n}{2}, \\ & \mathbf{v}_i \in \mathbb{R}^n, \quad \|\mathbf{v}_i\|_2 = 1. \end{aligned}$$

$$\begin{aligned} \max_{\mathbf{s}} \quad & \mathbf{s}^\top \mathcal{D}(\mathbf{L}) \mathbf{s}, \\ \text{s.t.} \quad & \|\mathbf{s}\|_0 = k, \\ & \mathbf{s} \in [0, 1]^n. \end{aligned}$$

The scale does not influence approximation ratio.

Solve Limited-information Problem with Semidefinite Programming

$$\begin{aligned} \max_{\mathbf{v}_1, \dots, \mathbf{v}_n} \quad & \frac{1}{4} \sum_{ij} \mathcal{D}(\mathbf{L})_{ij} \mathbf{v}_i^\top \mathbf{v}_j, \\ \text{s.t.} \quad & \sum_{i < j} \mathbf{v}_i^\top \mathbf{v}_j = \frac{1}{2} n^2 (1 - 2\alpha)^2 - \frac{n}{2}, \\ & \mathbf{v}_i \in \mathbb{R}^n, \quad \|\mathbf{v}_i\|_2 = 1. \end{aligned}$$

Algorithm 1: SDP-based algorithm

Solve the SDP, obtain $\mathbf{v}_1, \dots, \mathbf{v}_n$;

for $T = 1, \dots, \mathcal{O}(1/\epsilon \log(1/\epsilon))$ **do**

- Sample vector \mathbf{r} with each entry
 $\sim \mathcal{N}(0, 1)$;
- Set $S = \{i : \langle \mathbf{v}_i, \mathbf{r} \rangle \geq 0\}$ and
 $\bar{S} = V \setminus S$;
- if** $|S| \neq \alpha n$ **then**
 - greedily move elements from S
(\bar{S}) to \bar{S} (S) until $|S| = \alpha n$

return best over T trials;

Solve Limited-information Problem with Semidefinite Programming

$$\begin{aligned} \max_{\mathbf{v}_1, \dots, \mathbf{v}_n} \quad & \frac{1}{4} \sum_{ij} \mathcal{D}(\mathbf{L})_{ij} \mathbf{v}_i^\top \mathbf{v}_j, \\ \text{s.t.} \quad & \sum_{i < j} \mathbf{v}_i^\top \mathbf{v}_j = \frac{1}{2} n^2 (1 - 2\alpha)^2 - \frac{n}{2}, \\ & \mathbf{v}_i \in \mathbb{R}^n, \quad \|\mathbf{v}_i\|_2 = 1. \end{aligned}$$

Let M^* be the optimal solution of SDP.
Let $\text{cut}(S)$ be the cut if S consists of one partition, after hyperplane rounding.

- $\mathbb{E}\left[\frac{\text{cut}(S)}{M^*}\right] \geq \frac{\pi}{2}$.
- $\mathbb{E}[|S| \mid \bar{S}] \geq 0.878 n^2 (1 - \alpha) \alpha$.
- \Rightarrow Markov inequality: $\exists S$
 $\frac{\text{cut}(S)}{M^*} + \frac{|S| \mid \bar{S}|}{n^2 \alpha (1 - \alpha)} \geq (1 - \epsilon) \left(\frac{\pi}{2} + 0.878\right)$.

Solve Limited-information Problem with Semidefinite Programming

$$\begin{aligned} \max_{\mathbf{v}_1, \dots, \mathbf{v}_n} \quad & \frac{1}{4} \sum_{ij} \mathcal{D}(\mathbf{L})_{ij} \mathbf{v}_i^\top \mathbf{v}_j, \\ \text{s.t.} \quad & \sum_{i < j} \mathbf{v}_i^\top \mathbf{v}_j = \frac{1}{2} n^2 (1 - 2\alpha)^2 - \frac{n}{2}, \\ & \mathbf{v}_i \in \mathbb{R}^n, \quad \|\mathbf{v}_i\|_2 = 1. \end{aligned}$$

Let M^* be the optimal solution of SDP. Let $\text{cut}(S)$ be the cut if S consists of one partition, after hyperplane rounding. Let S' be the set of nodes in one partition.

- Markov inequality: $\exists S$
 $\frac{\text{cut}(S)}{M^*} + \frac{|S||\bar{S}|}{n^2\alpha(1-\alpha)} \geq (1-\epsilon)(\frac{\pi}{2} + 0.878).$
- Moving one node from S' to \bar{S}' loses $\frac{2\text{cut}(S')}{|S'|}.$

Solve Limited-information Problem with Semidefinite Programming

$$\begin{aligned} \max_{\mathbf{v}_1, \dots, \mathbf{v}_n} \quad & \frac{1}{4} \sum_{ij} \mathcal{D}(\mathbf{L})_{ij} \mathbf{v}_i^\top \mathbf{v}_j, \\ \text{s.t.} \quad & \sum_{i < j} \mathbf{v}_i^\top \mathbf{v}_j = \frac{1}{2} n^2 (1 - 2\alpha)^2 - \frac{n}{2}, \\ & \mathbf{v}_i \in \mathbb{R}^n, \quad \|\mathbf{v}_i\|_2 = 1. \end{aligned}$$

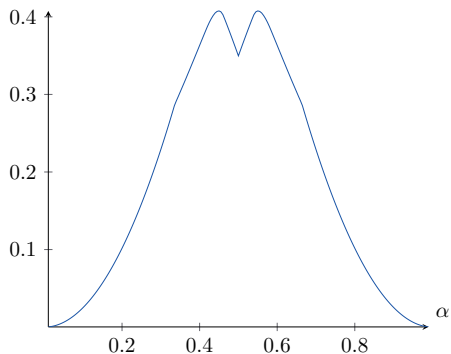


Figure: Approximation Ratio. $k = \alpha n$.

Interventions as Optimization Problems

Objective function encodes the desired goal; Constraints encode the power of the intervention.

- Musco, Musco, Tsourakakis (WebConf'18):
 - Suppose we can change the network structure such that the sum of degree keeps the same, then minimizing the sum of disagreement and polarization is a convex optimization problem.
- Chitra, Musco (WSDM'20):
 - If OSN providers repeatedly change the network structure to reduce disagreement, this will increase the polarization.
- Tu, Neumann (WebConf'22):
 - Model for simulating how viral content in OSNs impacts user opinions, and increase polarization.